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Color classification methods :

- Clusters of colors in the color space
- Modes in color histograms

Spatio-colorimetric classification : introduction of spatial information in the attributes to classify

Classical classification methods using extended attributes: vector of neighbors pixels [Ferri 92], Neural network [Campadelli 97], Fuzzy classification [Noordam 00], Homogram [Cheng 03]: fuzzy homogeneity vectors.

Pyramid of connectedness degrees [Fontaine 01], Spatial color compactness degree [Macaire 06].

Our approach:

Use of the **connectedness degree** in a more time-effective classification method.

I. The connectedness degree

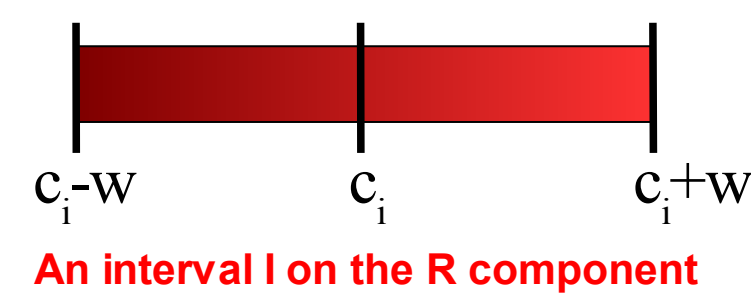
First order probability of a color interval

Trichromatic components $c_i = (c_1, c_2, c_3)$

Monochromatic color intervals of size $2w+1$: $I(c_i, w) = [c_i - w, c_i + w]$

First order probability of a color interval :

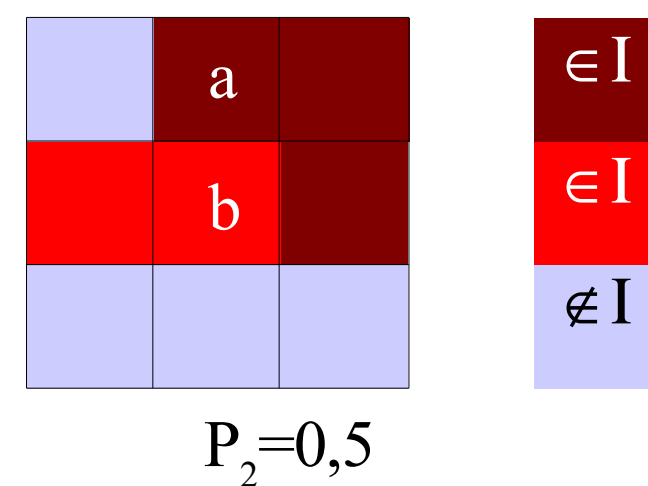
$$P_1(I(c_i, w)) = \sum_{a \in I(c_i, w)} P_i(a)$$



Second order probability of a color interval

Occurrence probability $P_{oc}(a, b)$: probability that colors a and b are neighbors (8-connectedness)

Co-occurrence probability $P_{cc}(a, b) = \frac{1}{8} \sum_{a \in N(b)} P_{oc}(a, b)$



Second order probability of a color interval:

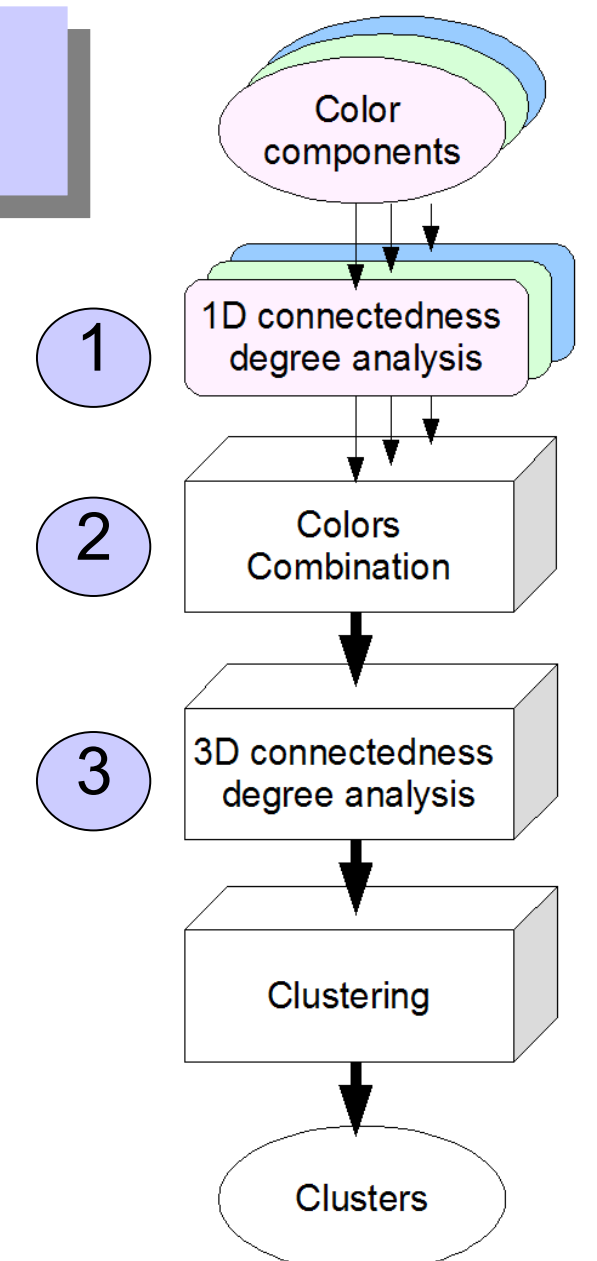
$$P_2(I(c_i, w)) = \sum_{a \in I(c_i, w)} \sum_{b \in I(c_i, w)} P_{cc}(a, b)$$

Connectedness degree

$$D(I(c_i, w)) = \frac{P_2(I(c_i, w))}{P_1(I(c_i, w))}$$

- **Property:** **maximun** when the interval $I(c_i, w)$ corresponds to one or several connected components in the image, i.e. to a **meaningful color interval** in terms of connectedness.
- **Previous works on the connectedness degree :**
 - [Fontaine00]: gray images, multi-level 2D data structure.
By analyzing various sizes of intensity interval, the relevant intensity classes are computed by extracting some *signatures* in this representation.
 - [Fontaine01]: extension to color.
 - Multi-level pyramid of connectedness for each bichromatic histogram.
 - 3 pyramids are required to extract each meaningful color interval : not time-effective.

II. The procedure, in 3 stages



1 Marginal analysis of color connectedness degree on each color component independently.

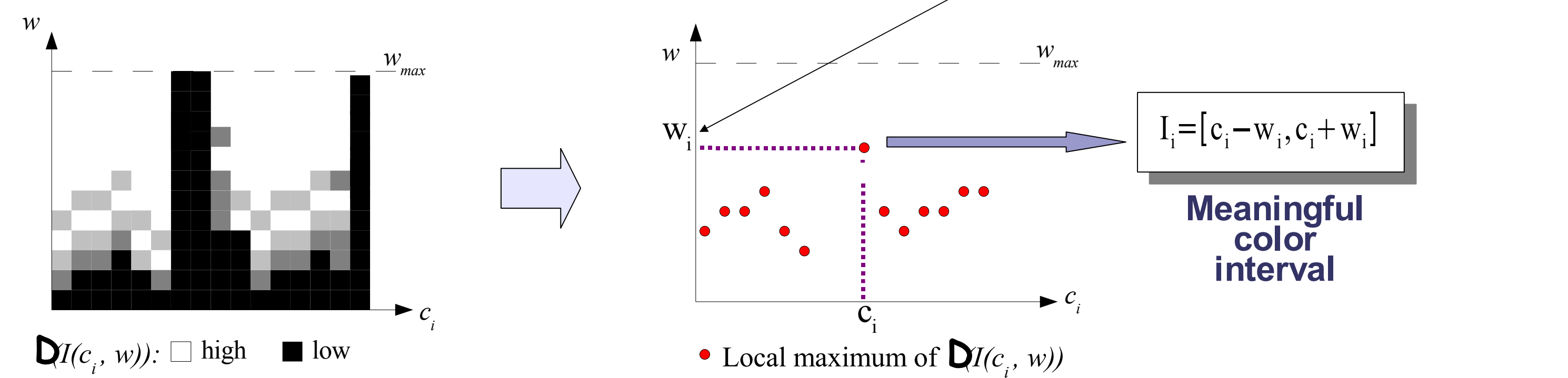
- Extraction of the most meaningful color intervals on each color component (local maxima of degree)
- Reduction of the number of monochromatic colors

2 Combination of colors

3 Vectorial analysis: analysis of the trichromatic connectedness degrees.

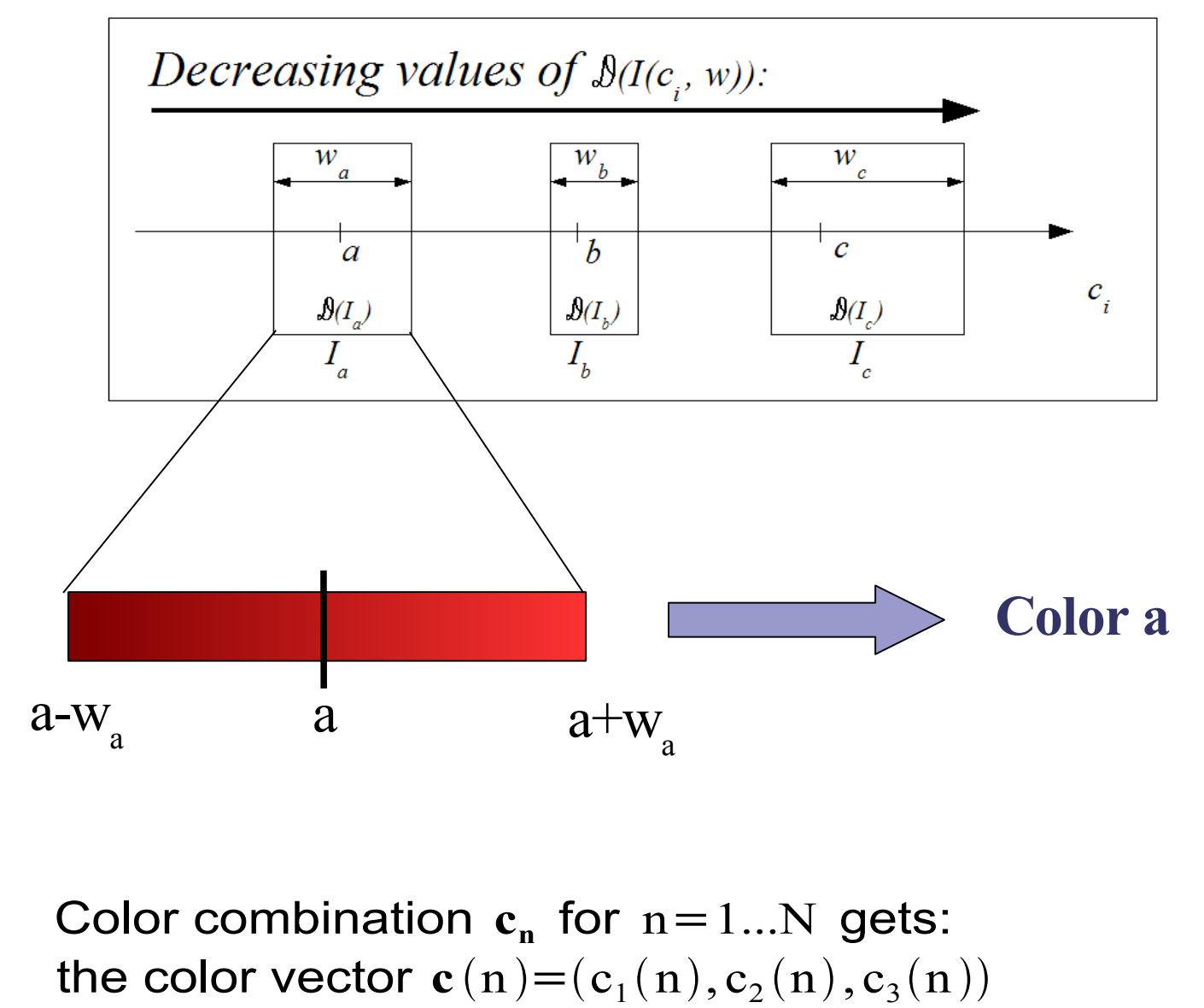
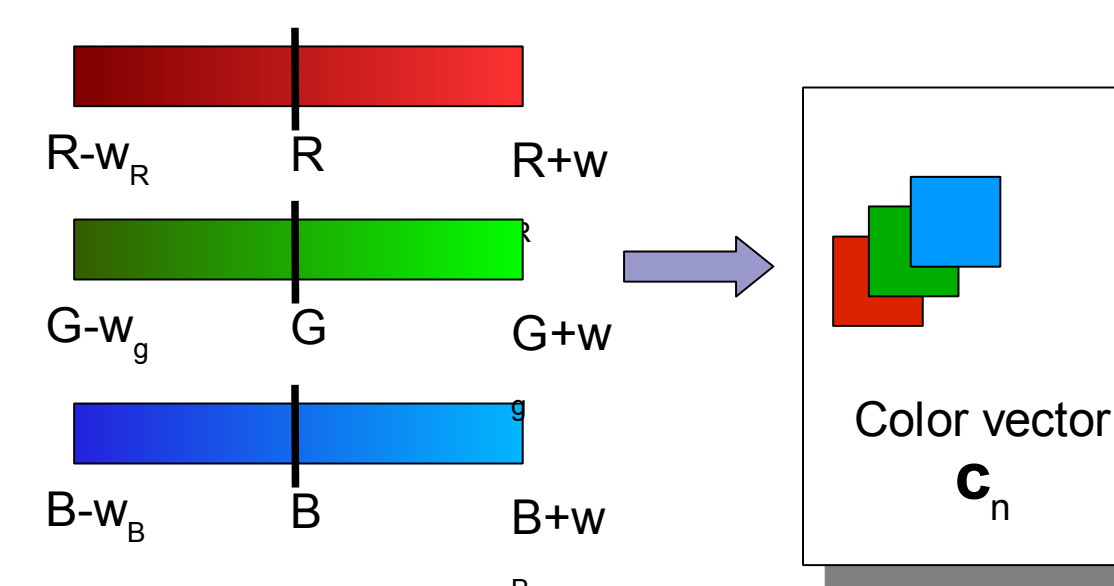
1 First stage : marginal analysis

Searching for local maxima of connectedness degree for $w=1 \dots w_{max}$



2 Color combination

- Color are sorted in decreasing order of degree
- Pixels are classified in that order
- Reduction of the number of colors: each color of the interval inherits the centroid color and will not be treated anymore by a less relevant interval.

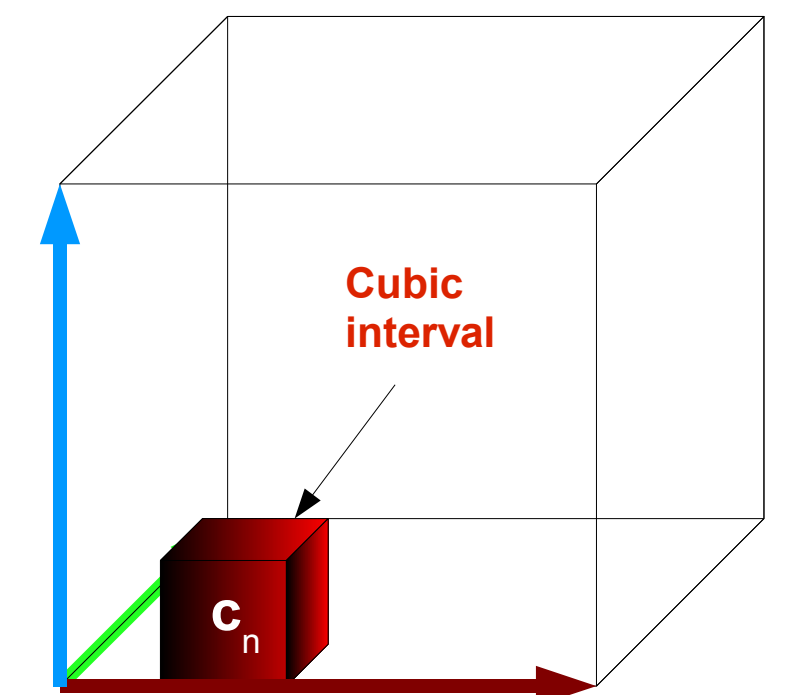


3 Vectorial analysis: similar analysis as the stage 1 but 3D intervals are considered.

Cubic color interval $I(c_n, d)$ in the color space, centered around the color $c(n)$ and of size $(2d+1, 2d+1, 2d+1)$:

For $n=1..N$ and $d < d_{max}$:

$$I(c_n, d) = \begin{bmatrix} c_1(n) - d, c_1(n) + d \\ c_2(n) - d, c_2(n) + d \\ c_3(n) - d, c_3(n) + d \end{bmatrix}$$



1st order probability of the 3D interval:

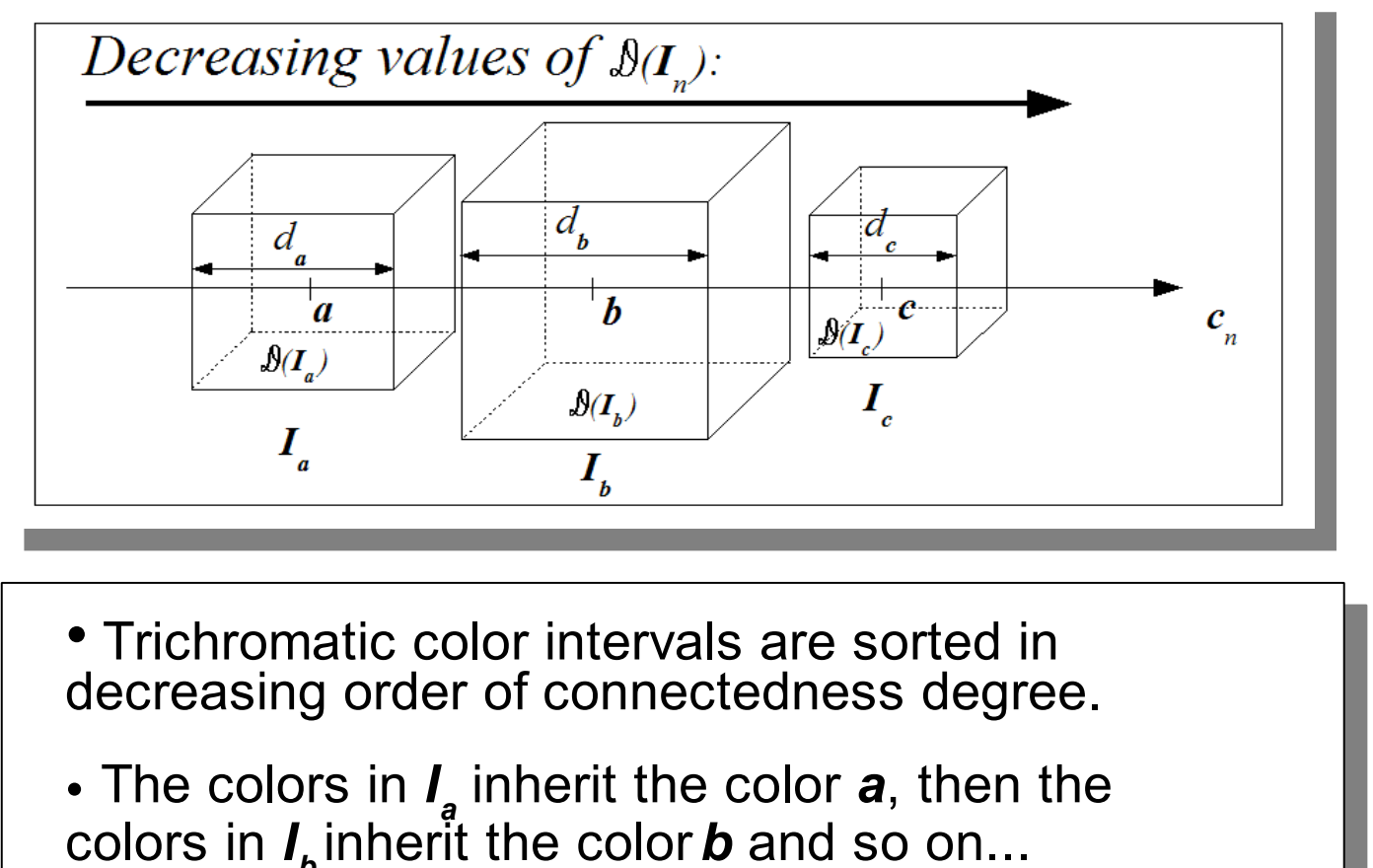
First order probabilities $P_1(I(c_n, d))$ of the colors intervals $I(c_n, d)$:
 $P_1(I(c_n, d)) = \sum_{a \in I(c_n, d)} P_i(a)$
where $P_i(a)$ is the occurrence probability of the color a .

2nd order probability of the 3D interval:

Second order probabilities $P_2(I(c_n, d))$ of the colors intervals $I(c_n, d)$:
 $P_2(I(c_n, d)) = \sum_{a \in I(c_n, d)} \sum_{b \in I(c_n, d)} P_{cc}(a, b)$
where the co-occurrence probabilities $P_{cc}(a, b)$ of two colors a and b are computed as:
 $P_{cc}(a, b) = \frac{1}{8} \sum_{a \in N(b)} P_{oc}(a, b)$
considering the 8-connectivity and a neighborhood N around b .

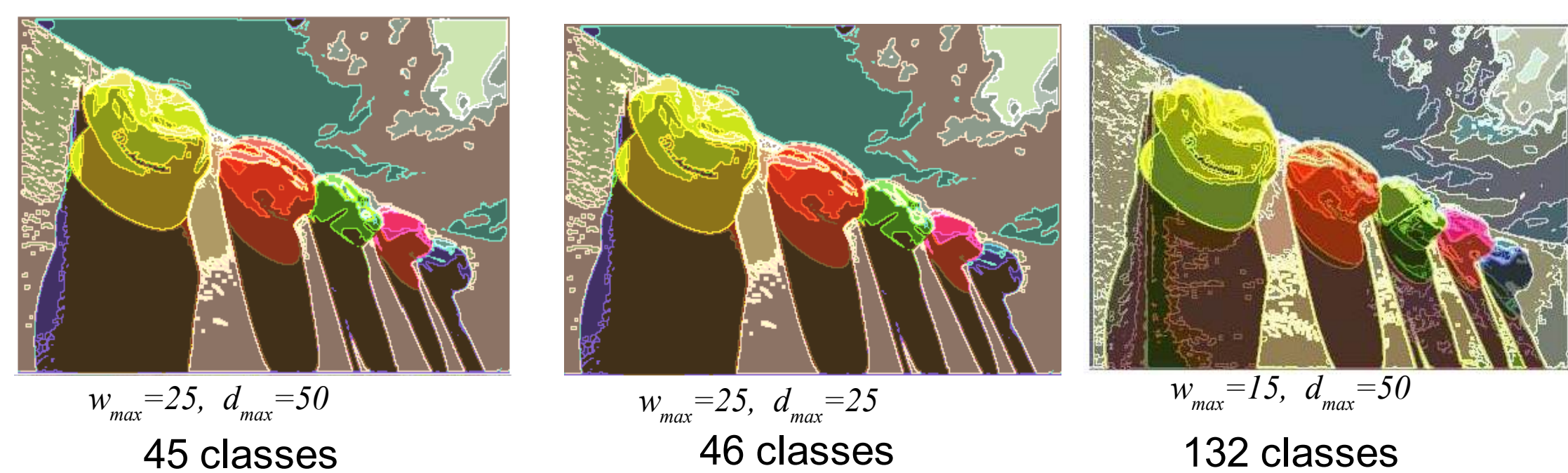
Connectedness degree of the 3D interval:

Connectedness degree $D(I(c_n, d))$ of the interval $I(c_n, d)$:
 $D(I(c_n, d)) = \frac{P_2(I(c_n, d))}{P_1(I(c_n, d))}$

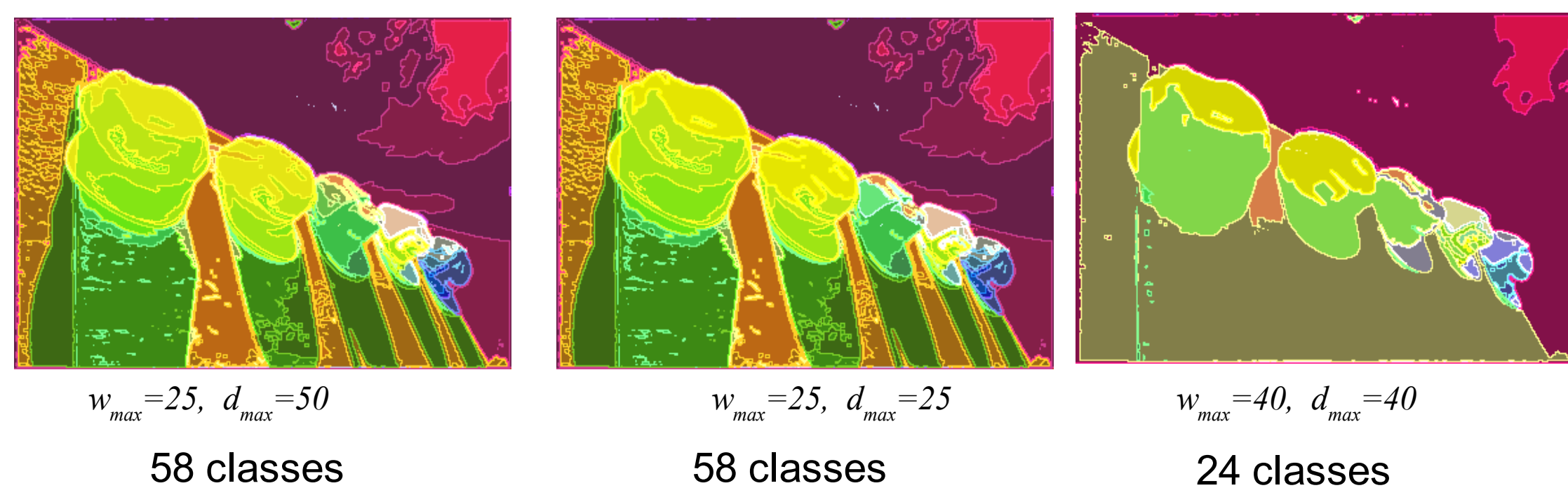


III. Results

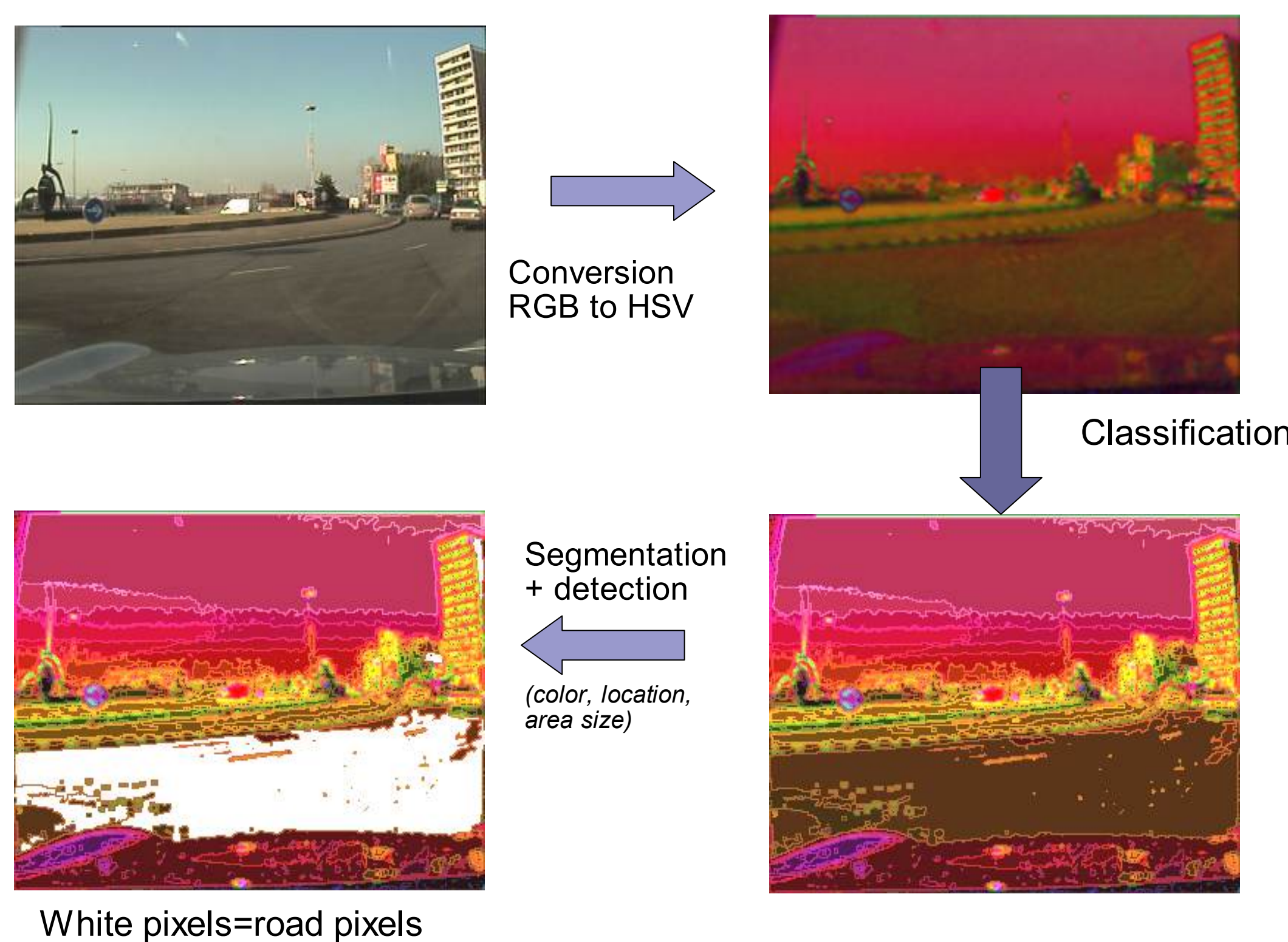
RGB



HSV



Example of application: segmentation of the road (for obstacles detection)



Example of result with :
 $d_{max} = w_{max} = 10\%$ of image range

